

# Asymmetric Steady Thermal Blooming

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**Abstract:** The thermal blooming of a Thulium laser near  $2\mu\text{m}$  in an enclosed chamber is considered, as in [1]. The problem is modeled using the paraxial equation for the laser and the Navier–Stokes equations with a Boussinesq approximation for buoyancy driven effects. These equations are solved numerically in the steady experimental configuration. The numerical procedure uses Radial Basis Functions (RBFs) to approximate spatial derivatives and the hybrid Padé–Newton approach of [2] to solve the resulting system of nonlinear equations. Numerical simulations are compared to experimental results. The simulations explain the asymmetry of laser spots as the result of the influence of the tank’s boundary on the global convective flow.

## 1. Introduction

In this work, the steady thermal blooming of a laser beam propagating through a closed laboratory chamber is discussed. This study is a continuation of the work performed in Chapter 5 of the first author’s PhD thesis [3]. Thermal blooming is the process wherein a laser heats the propagation medium, causing temperature-based changes in the refractive index in the beam path [4, 5]. This thermal lensing reduces beam performance. Adaptive optics countermeasures can result in phase compensation instability (PCI) [6–8], where adaptive phase corrections at the aperture can reinforce intensity aberrations in the target plane.

Numerical simulation of thermal blooming requires knowledge of the light field, the temperature distribution, and the fluid velocity. Historical studies prescribe the fluid velocity (either as a fixed wind or a statistical description) [9–14]. Recently, the time dependent nonlinear velocity field has been simulated directly including natural convection, from quiescent initial data [15, 16]. Steady thermal blooming with natural convection has also been simulated [17, 18]. Experimental studies in thermal blooming have considered beam propagation across a wide range of laser-fluid parameters such as beam power, beam wavelength, fluid medium, degree of turbulence, degree of cross-wind, and propagation distance [19–22]. While many of these studies are oriented towards understanding beam propagation through the atmosphere, there is scant discussion of the possible impact that the finite experimental domain may have on the beam wavefront via the laser-fluid interaction, especially in the steady-state regime. In this work the steady-state thermal blooming of a Gaussian laser with wavelength near  $\lambda \approx 2\mu\text{m}$  within a climate controlled, 5.3 meter long chamber is simulated and compared to experiment. The simulations result in asymmetric crescent shaped beam spots, providing an explanation for the observed asymmetries in the experiment. The influence of the experimental domain on the fluid dynamics of beam propagation is novel to the thermal blooming literature, with natural implications on experimental design for thermal blooming studies.

Both simulation and experimentation come with unique challenges when attempting to account for the fully coupled physical processes involved in laser propagation through an absorbing fluid. The steady fluid dynamics in response to the absorption of the beam are often dominated by natural convection, yet historical simulations for laser propagation have relied on a prescription of the fluid velocity via scaling laws or enforced crosswind [4, 5, 23]. To fully model the convective

48 flow dynamics within a prescribed domain, it is beneficial to directly simulate the flow response  
49 to the laser in a buoyancy-driven framework. A difficult limitation presented in the steady-state  
50 simulation [17, 18] is the reduction of computable laser forcing amplitudes of the fixed-point  
51 fluid solver as a function of increased domain size. Recent work by the authors, however, offers  
52 a composite Padé–Newton method to compute steady flow solutions for arbitrarily large laser  
53 forcing and domain size [2].

54 The goal of this article is two-pronged with contributions in the simulation of steady-state  
55 thermal blooming and the presentation of experimental results that describe new physical  
56 phenomena. We investigate the steady-state thermal blooming of a Gaussian laser tuned to  
57 a water absorption wavelength within a climate controlled, 5.3 meter long chamber. The  
58 specific tuning of the laser wavelength allows for significant absorption of the laser into the  
59 surrounding fluid [1, 24, 25], a strategy which can be used to represent high-power lasers through  
60 an atmospheric transmission window. We present evidence to suggest that if the beam propagates  
61 horizontally off-center within the fluid domain, then the bloomed irradiance in the target plane  
62 will be skewed in the direction of the nearest wall. In an effort to simulate this phenomenon,  
63 we introduce a fully-coupled steady-state simulation for thermal blooming that builds off of  
64 recent work by the authors to permit simulation for significant laser absorption over the full  
65 size of the experimental propagation chamber. We show that, due to the horizontally transverse  
66 displacement of the beam center along the propagation path, the temperature fluctuations in the  
67 chamber will induce asymmetric blooming in the horizontal direction.

68 The rest of the article is organized as follows. Section 2 details the experimental setup and  
69 Section 3 the formulation of the steady-state simulations. Section 4 is dedicated to the comparison  
70 of simulated and experimental results. We observe asymmetries in the bloomed irradiance  
71 profiles and present the fluid response to the tilted beam propagation. Section 5 summarizes the  
72 article and offers key takeaways for future experimental work in laser propagation.

## 73 2. Experimental Setup

74 The experimental setup depicting the propagation chamber is provided in Figure 1. The fiber  
75 laser architecture leading to the aperture is the same used in the experiments in [1]. The laser  
76 wavelength  $\lambda$  is tunable between  $1.92\ \mu\text{m}$  and  $2.01\ \mu\text{m}$  with a maximum average power of 80 W in  
77 continuous wave operation. In the following experiments, the variable power laser is a Gaussian  
78 beam with a radius of 2.25 mm and a fixed wavelength of 1944.867 nm to correspond to a water  
79 absorption band. After passing through the aperture, the beam enters the atmosphere-controlled  
80 propagation chamber with initially quiescent flow. The chamber is filled with air at atmospheric  
81 pressure, with the same conditions as the thermal blooming experiments in [1]. The relative  
82 humidity was 50% and the fluid temperature was 296 K. The beam reflects off of a movable  
83 ceramic backstop and the resultant irradiance profile is imaged with a FLIR camera through  
84 windows along the side of the chamber.

85 In an attempt to remove optical backscatter, the beam is initially reflected twice such that  
86 the resulting path traveling through the chamber is tilted in the transverse, horizontal direction.  
87 Figure 2 diagrams a top-down view of the propagation chamber, depicting the initial reflections  
88 and the subsequent horizontal tilting of the beam. Figure 3 provides a detailed description of the  
89 (not to scale) geometry of the mirror arrangements within the chamber.

90 The tilting angle  $\theta$  is determined *a posteriori* via the horizontal separation of the beam spot  
91 between two propagation distances. We observe a horizontal shift in the beam spot of 1 cm  
92 for every 1 m of longitudinal propagation, so the effective tilting angle is  $\theta \approx 0.01$  rad; small  
93 enough to maintain the validity of the paraxial model for beam evolution. The beam reflects off  
94 of the second mirror at a location of  $x_0 = -8.9$  cm relative to the transverse center of the domain  
95 and reflects off of the ceramic backstop at a location of  $x_f = -4.9$  cm for 5 m of propagation.  
96 The beam is centered vertically throughout the propagation chamber, with vertical variations

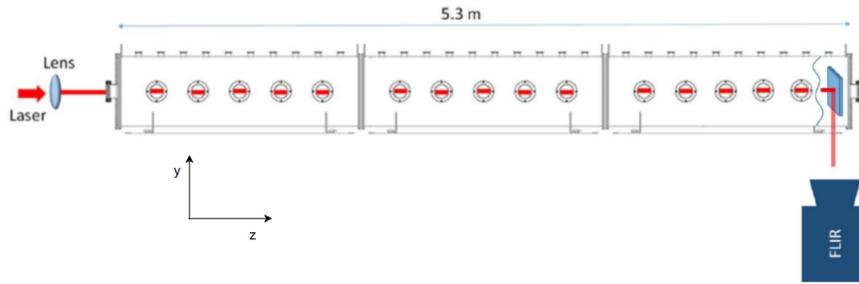


Fig. 1. Side view of the propagation chamber with coordinate axes.

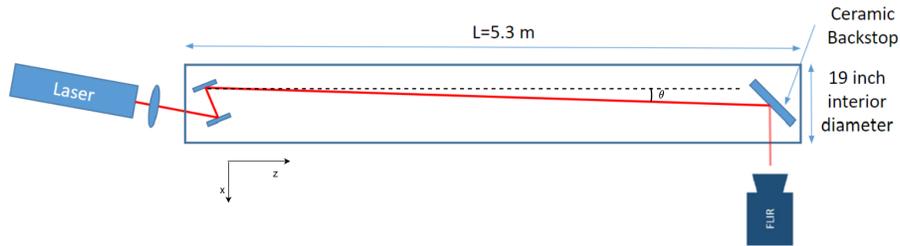


Fig. 2. Top down view of the chamber.

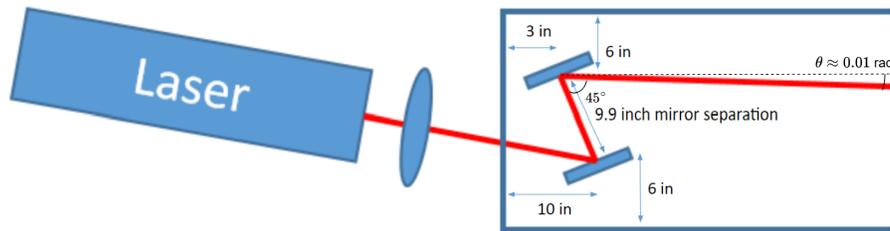


Fig. 3. Zoomed-in view of the chamber with the tilting angle  $\theta$ . Since the initial reflections are not simulated, the first incident angle is not specified.

97 in intensity due exclusively to thermal blooming. The FLIR camera captures the time dynamic  
 98 laser irradiance with a frequency of 100 Hz and a frame integration time of 928  $\mu$ s.

### 99 3. Numerical Methods

#### 100 3.0.1. Governing Models

101 The paraxial equation is used as a model for the laser propagation [26]. With the same order of  
 102 accuracy as the paraxial scaling for the evolution of the laser, the fluid flow is two-dimensional  
 103 in the transverse plane [15]. This simulation architecture forms the basis of the steady-state  
 104 simulation developed in [18], where the steady-state flow is computed along two-dimensional slices  
 105 across the propagation direction and the fluid temperature fluctuations are linearly interpolated  
 106 between transverse slices.

107 The fluid is assumed to be incompressible and governed by the Boussinesq approximation  
 108 for buoyancy-driven flows. Since the simulated flow is two-dimensional, we solve the stream

109 function-vorticity form of the nondimensional governing equations [27],

$$(\mathbf{u} \cdot \nabla)T = \frac{1}{\text{Pe}} \nabla^2 T + \text{St}|V|^2, \quad (1a)$$

$$(\mathbf{u} \cdot \nabla)\omega = \frac{1}{\text{Re}} \nabla^2 \omega + \text{Ri} \partial_x T, \quad (1b)$$

$$\nabla^2 \psi = -\omega, \quad (1c)$$

$$u = \partial_y \psi, \quad v = -\partial_x \psi, \quad (1d)$$

110 with vorticity  $\omega = \partial_x v - \partial_y u$ , stream function  $\psi$ , temperature fluctuation  $T$ , flow velocity  
 111  $\mathbf{u} = (u, v)$ , and normalized laser irradiance  $|V|^2$ . The nondimensional parameters are, respectively,  
 112 the Peclet (Pe), Reynolds (Re), Richardson (Ri), and Stanton (St) numbers defined below.

$$\text{Re} = \frac{L_x}{\nu}, \quad \text{Pe} = \frac{L_x}{\mu}, \quad \text{Ri} = gL_x, \quad \text{St} = \frac{\beta V_0^2 L_x}{\tau_0}. \quad (2)$$

113 There is an implicit assumption of a characteristic velocity  $U = 1$  cm/s for each of the  
 114 nondimensional parameters, which can be set arbitrarily without impacting the flow. The  
 115 parameters to match the experiment are the length scale  $L_x = 0.225$  cm as the beam radius, the  
 116 acceleration due to gravity  $g = 981$  cm/s<sup>2</sup>, the kinematic viscosity  $\nu = 0.15$  cm<sup>2</sup>/s, the thermal  
 117 diffusivity  $\mu = 0.2$  cm<sup>2</sup>/s, the temperature scale  $\tau_0 = 296$  K, the laser-fluid absorption constant  
 118  $\beta = 4.02 \frac{\text{cm}^2 \text{K}}{\text{J}}$ , and the peak aperture laser intensity  $V_0^2$ , which varies between 18.9 W/cm<sup>2</sup> and  
 119 68.3 W/cm<sup>2</sup>. The Re, Pe, and Ri numbers take on the values Re = 1.5, Pe = 1.125, and Ri = 220.7.  
 120 The Stanton number can be thought of as a measure of the heat deposition from the laser into  
 121 the flow, and thus depends on the product of the laser irradiance with the laser-fluid absorption  
 122 constant  $\beta$ . This parameter is related to the more common extinction coefficient  $\alpha$  via  $\beta = \frac{\alpha}{\rho c_p}$ ,

123 where  $\alpha = 0.48$  m<sup>-1</sup> is the estimate for the extinction coefficient the laser wavelength within the  
 124 water absorption band, obtained from the previous experiments with the same chamber [1].

125 The beam amplitude  $V$  is evolved according to the paraxial equation in nondimensional  
 126 units [28],

$$\frac{\partial V}{\partial z} = \left( \frac{i}{2n_0 F} \nabla_{\perp}^2 - iL_z n_1 k - \frac{L_z}{2} \alpha \right) V, \quad (3)$$

127 where  $F = \frac{L_x^2 k}{L_z}$  is the Fresnel number [4, 5],  $L_z$  is the propagation distance of either 3 m or 5  
 128 m,  $\nabla_{\perp}^2$  is the Laplacian in the transverse (x,y)-plane,  $k = \frac{2\pi}{\lambda} = 3.23065 \times 10^4$  cm<sup>-1</sup> is the laser  
 129 wavenumber,  $n_0 = 1.0003$  is the ambient refractive index for air, and  $\alpha$  is the same extinction  
 130 coefficient defined above. The refractive index fluctuation  $n_1$  is related linearly to the spatially  
 131 varying fluid temperature fluctuations according to  $n_1(x, y, z) = (1 - n_0)T(x, y, z)$  [29]. The  
 132 coupling of the beam response to the fluid is thus contained in this fluctuation. The normalized  
 133 and nondimensional beam amplitude  $V_0$  at the beginning of propagation takes the form of a  
 134 Gaussian with a Zernike tilt aberration [30] such that

$$V_0(x, y) = e^{iL_x k \theta x} e^{-\left( \left( x - \frac{x_0}{L_x} \right)^2 + y^2 \right)}. \quad (4)$$

135 Table 1 summarizes each of the parameter values for the experiments and simulation.

### 136 3.0.2. Solution Methods

137 To solve for the steady flow solutions to the Boussinesq equations (1), a Padé–Newton procedure  
 138 is used [2]. The method presented in [2] is extended to allow for irregular domains, using Radial

Parameter	Description	Value	Units
$\lambda$	Wavelength	1944.867	nm
$k$	Wavenumber	$3.23065 \cdot 10^4$	$\text{cm}^{-1}$
$L_x$	Beam Radius/Length Scale	2.25	mm
$\tau_0$	Ambient Temperature	296	K
$\nu$	Kinematic Viscosity	0.15	$\text{cm}^2/\text{s}$
$\mu$	Thermal Diffusivity	0.2	$\text{cm}^2/\text{s}$
$g$	Gravitational Acceleration	981	$\text{cm}/\text{s}^2$
$\beta$	Laser-Fluid Absorption Constant	4.02	$\frac{\text{cm}^2\text{K}}{\text{J}}$
$\alpha$	Extinction Coefficient	0.48	$\text{m}^{-1}$
$n_0$	Ambient Refractive Index	1.0003	–
$D$	Domain Width	42	cm
$\theta$	Beam Tilt Angle	0.01	rad
$x_0$	Initial Beam Location	-8.9	cm
Re	Reynolds Number	1.5	–
Pe	Peclet Number	1.125	–
Ri	Richardson Number	220.7	–

Table 1. Fixed Parameters

Power	$V_0^2$	St
1.5 W	18.9 W/cm <sup>2</sup>	0.0541
2.5 W	31.4 W/cm <sup>2</sup>	0.0901
3.5 W	44.0 W/cm <sup>2</sup>	0.1262
4.5 W	56.6 W/cm <sup>2</sup>	0.1622
5.43 W	68.3 W/cm <sup>2</sup>	0.1958

Propagation Distance	Fr
3 m	5.45
5 m	3.27

Table 2. Variable Parameters

139 Basis Functions to approximate differential operators [16, 31, 32]. The flow is assumed to be  
140 two-dimensional along a transverse slice of the propagation chamber at the longitudinal location  
141  $z_j$ .

142 Spatial derivatives in the direction transverse to the beam propagation were approximated  
143 using Radial Basis Function generated Finite Differences (RBF-FD) [33–38]. RBF-FD methods  
144 are capable of efficiently handling problems that benefit from nonuniform discretizations. In  
145 particular, they are useful when attempting to resolve rapidly changing features in the solution  
146 to a PDE [31]. A description of their implementation is provided in the appendix, where the  
147 RBF interpolants used here utilize the Polyharmonic Spline RBF  $\phi(r) = r^7$  and supplemental

148 bivariate polynomials up to degree  $m = 7$ . Figure 4 illustrates the 2D computational fluid domain  
 149 with circular geometry.

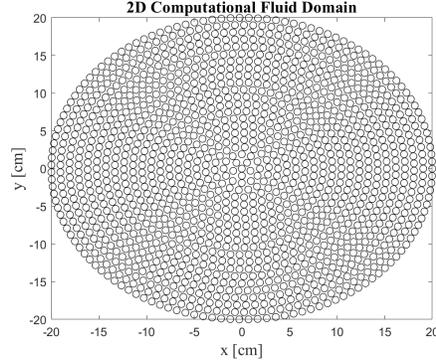


Fig. 4. Illustration of the computational fluid domain with meshless nodes used in the RBF-FD method. The maximum node spacing depicted is  $h = 1$ , but the simulations were carried out with a more refined  $h = 0.125$ .

150 The stream function and vorticity are enforced to be zero on the boundary, corresponding  
 151 to a Navier slip boundary condition where the normal component of velocity at the boundary  
 152 vanishes but the tangential component is not necessarily zero. We also enforce a zero boundary  
 153 condition for the temperature fluctuation, that assumes perfect conduction of heat out of the  
 154 chamber. Along the first fluid slice at  $z = 0$ , we apply directly the Padé–Newton method by first  
 155 expanding the flow variables in a perturbation series in the St number,

$$T = \sum_{n=0}^{\infty} St^n T_n, \quad \omega = \sum_{n=0}^{\infty} St^n \omega_n, \quad \psi = \sum_{n=0}^{\infty} St^n \psi_n, \quad (5)$$

156 where each term in the series is computed via the numerical solution to a linear Poisson equation  
 157 using an RBF-FD discretization. This series representation is analytic only for small values of  
 158 the St number, so we compute a functional Padé approximant in each flow variable of the form

$$r^{[n/2k]}(x, y; \epsilon) = \frac{p(x, y; St)}{q(St)}. \quad (6)$$

159 The numerator  $p(x, y; St)$  and denominator  $q(St)$  polynomials are functions of the series terms for  
 160 each respective flow variable. The spatial dependence in  $(x, y)$  is contained only in the numerator  
 161 polynomial while the denominator polynomial is strictly a scalar function of St.

162 In our experiments, the St number is large enough that the functional Padé approximant on  
 163 its own fails to represent the steady flow to a sufficient degree of accuracy. We thus use the  
 164 functional Padé approximant as an initialization for a Newton iteration of the form

$$\mathbf{X}_{n+1} = \mathbf{X}_n - J(\mathcal{F}(\mathbf{X}_n))^{-1} \mathcal{F}(\mathbf{X}_n), \quad (7)$$

165 where  $\mathbf{X}_n = (T_n, \omega_n, \psi_n)$ ,  $\mathcal{F}(\mathbf{X}_n)$  contains the roots of the steady flow equations (1) with the initial  
 166 laser intensity, and  $J$  denotes the Jacobian of  $\mathcal{F}$  at  $\mathbf{X}_n$ .

167 To evolve the beam amplitude  $V$  via the Paraxial equation, we linearly interpolate the  
 168 temperature fluctuations within the volumetric space between two fluid slices. A Fourier  
 169 split-step scheme is used to evolve the numerical solution between slices in  $z$ .

170 Given a known steady flow and beam amplitude at the slice  $z_j$ , the computation of the fluid  
 171 slice at the  $z_{j+1}$  position requires an iteration in the temperature fluctuation and beam amplitude.

172 Letting  $T^k$  and  $V^k$  be the temperature and laser amplitude at the  $k$ th fluid slice, a sequence of  
 173 guesses for the temperature  $\{\mathcal{T}_n\}$  and the amplitude  $\{\mathcal{V}_n\}$  is produced at the next  $(k + 1)$ st slice  
 174 with an initialization

$$\mathcal{T}_0 = T^k, \quad \mathcal{V}_0 = V^k. \quad (8)$$

175 These iterative variables are then evolved by implementing the paraxial and fluid solvers, where  
 176  $T^*(\mathcal{V})$  is the steady temperature fluctuation obtained from the fluid equations for an irradiance  
 177  $|\mathcal{V}|^2$  and  $V^*(\mathcal{T}_i, \mathcal{T}_j)$  is the numerical solution to the paraxial equation between two slices with  
 178 temperature fluctuations  $\mathcal{T}_i$  and  $\mathcal{T}_j$ , respectively. The iteration is defined by

$$\mathcal{V}_{n+1} = V^*(T^k, \mathcal{T}_n), \quad (9a)$$

$$\mathcal{T}_{n+1} = T^*(\mathcal{V}_{n+1}). \quad (9b)$$

179 The initialization for the Newton iteration in computing the step  $T^*(\mathcal{V}_{n+1})$  is the previous  
 180 flow solution  $T^*(\mathcal{V}_n)$ . If any fluid computational step fails to converge, we apply numerical  
 181 continuation in St for the same normalized amplitude  $\mathcal{V}$ . Convergence is achieved when the fluid  
 182 response and laser amplitude changes are less than a prescribed threshold, i.e.

$$\|\mathcal{T}_{\mathcal{N}} - \mathcal{T}_{\mathcal{N}-1}\| < \delta_T, \quad \|\mathcal{V}_{\mathcal{N}} - \mathcal{V}_{\mathcal{N}-1}\| < \delta_V \quad (10)$$

183 for  $\delta_T = \delta_V = 10^{-15}$ . After convergence, the fluid temperature and laser amplitude at the  
 184  $(k + 1)$ th slice are then updated as

$$T^{k+1} = \mathcal{T}_{\mathcal{N}}, \quad V^{k+1} = \mathcal{V}_{\mathcal{N}}. \quad (11)$$

## 185 4. Results

186 We apply the simulation outlined above to compare each of the propagation distances and beam  
 187 powers performed in the experiment. The experimental results are captured in a time-dynamic  
 188 image of intensity over a square window approximately 12 cm wide. The imaging is performed  
 189 over a time window of 19.6 s, with a dead time of approximately 1 s before the laser is turned on  
 190 at  $t = 0$  s. The most significant time dynamics occur over a short time span of approximately 0.05  
 191 s, with the beam approaching an observable steady-state intensity profile from near 0.25 s to the  
 192 end of the imaging period at 18.7 s. Figure 5 depicts the time evolution of the experimental beam  
 193 for propagation over 5 m at 5.43 W. The image plane is oriented such that the resultant crescent  
 194 is biased away from the direction of the beam tilt and in the direction of the wall closest to the  
 195 beam spot, as diagrammed in Figures 2 and 3.

196 Since our simulation ignores optical aberrations such as turbulence, speckle, or jitter, we  
 197 average the experimental intensity over the final 10 s of image capture. This approach provides  
 198 a better basis of comparison for the predicted mathematical steady-state as any time dynamic  
 199 fluctuations will be smoothed out. This averaging is performed for each experimental image  
 200 depicted in Figures 6 and 7.

201 In the simulation, the discretization of the fluid and the laser are treated differently due to  
 202 considerations of computational cost and required resolution to resolve the frequency components  
 203 arising from the beam tilt. Thus, the 2D fluid equations are solved through a discretization at  
 204 one resolution,  $h_f = 0.125$ , while the beam is evolved in the solver for the paraxial equation  
 205 between slices at a finer resolution  $h_L = 0.0039$ . This requires a transverse interpolation of  
 206 the temperature fluctuation over the location of the beam wavefront on top of the volumetric  
 207 interpolation between 2D slices, spaced according to  $\Delta z = 1$  cm. Applying this approach allows  
 208 for the simultaneous computation of the steady flow over the full experimental domain with the  
 209 highly resolved beam wavefront over a much smaller subdomain. Solutions were computed on a  
 210 workstation with 12 Intel Xeon processors, each running at 3.30 GHz, and 96 GB of memory

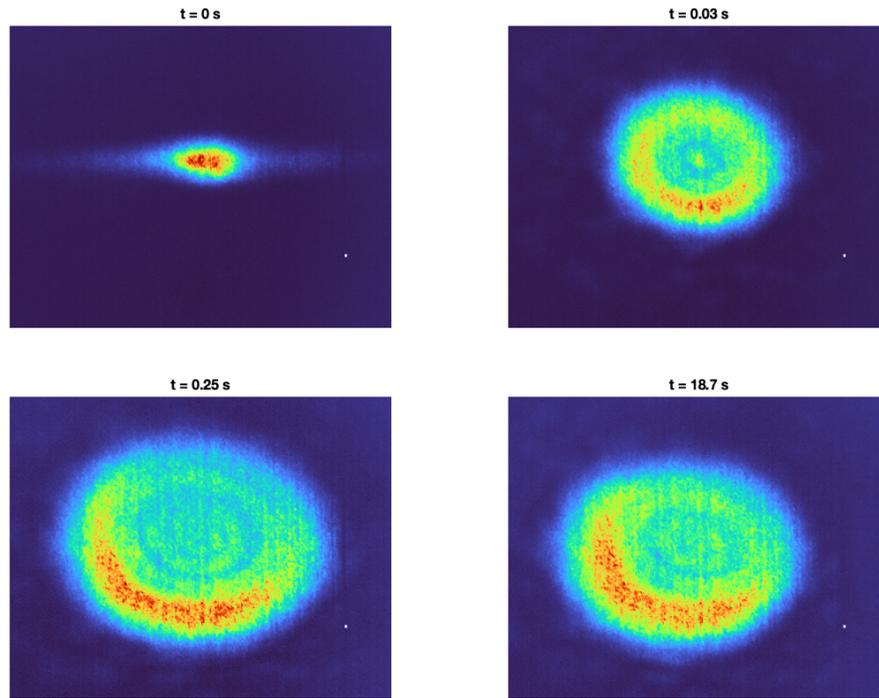


Fig. 5. The time evolution of the thermally bloomed beam within the experimental chamber is depicted. **Top Left:** The beam spot at  $t = 0$  displays no visible blooming. **Top Right:** The beam profile at  $t = 0.03$  s by which time most of the dynamics have occurred. **Bottom Left:** The beam profile at  $t = 0.25$  s as the beam response approaches steady state. **Bottom right:** The averaged beam profile at the final imaging frame is essentially unchanging.

211 running MATLAB R2023b. The simulations ran for approximately four days for each beam  
 212 power compared in Figures 6 and 7.

213 Figures 6 and 7 provide a direct comparison between the steady-state experimental and  
 214 simulated intensity after 3 m and 5 m of propagation, respectively, for each of the average laser  
 215 powers. The irradiance spot is shown within a  $6\text{ cm} \times 6\text{ cm}$  window for both the experiment  
 216 and the simulation with the same image orientation as Figure 5. Figure 8 gives a plot of the  
 217 irradiance along a vertical centerline for the simulated and experimental beams.

218 The general shape and size of the beam spots agree well between experiment and simulation.  
 219 The width of the bloomed irradiance pattern increases with an increase in beam power to  
 220 approximately 3.5 cm for the 5.43 W beam. Both display noticeable asymmetry in the intensity  
 221 distribution in the horizontal direction. This is addition to the vertical deflection of the beam  
 222 spot due to convection that is well-documented in the thermal blooming literature [22, 39, 40].  
 223 Since our simulations directly solve for the fluid response to the laser heating within the full  
 224 experimental chamber, this diagonal deflection of the beam intensity is due to corresponding  
 225 asymmetries in the temperature fluctuation about the local wavefront within the propagation  
 226 chamber. With increasing beam power, the crescent in the irradiance pattern becomes more  
 227 pronounced, especially for the simulations. This is explained by the coupling between the  
 228 temperature fluctuations and the beam evolution as determined by the paraxial equation (3).  
 229 The temperature fluctuations surrounding the beam increase with increasing beam power, and



(a)  $P = 1.5$  W.



(b)  $P = 2.5$  W.



(c)  $P = 3.5$  W.

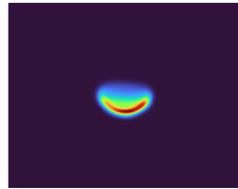
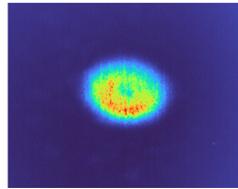


(d)  $P = 4.5$  W.

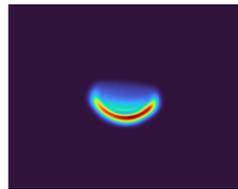
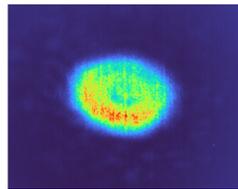


(e)  $P = 5.43$  W.

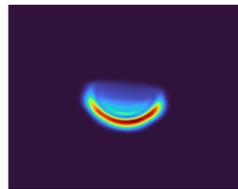
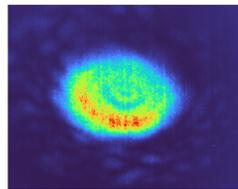
Fig. 6. Comparison between experiment (left) and simulation (right) after 3 m of propagation.



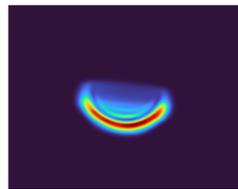
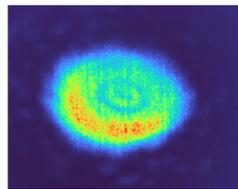
(a)  $P = 1.5$  W.



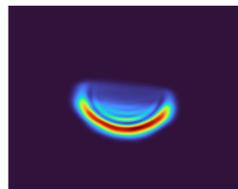
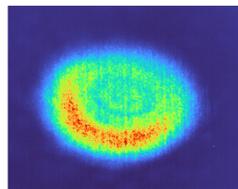
(b)  $P = 2.5$  W.



(c)  $P = 3.5$  W.



(d)  $P = 4.5$  W.



(e)  $P = 5.43$  W.

Fig. 7. Comparison between experiment (left) and simulation (right) after 5 m of propagation.

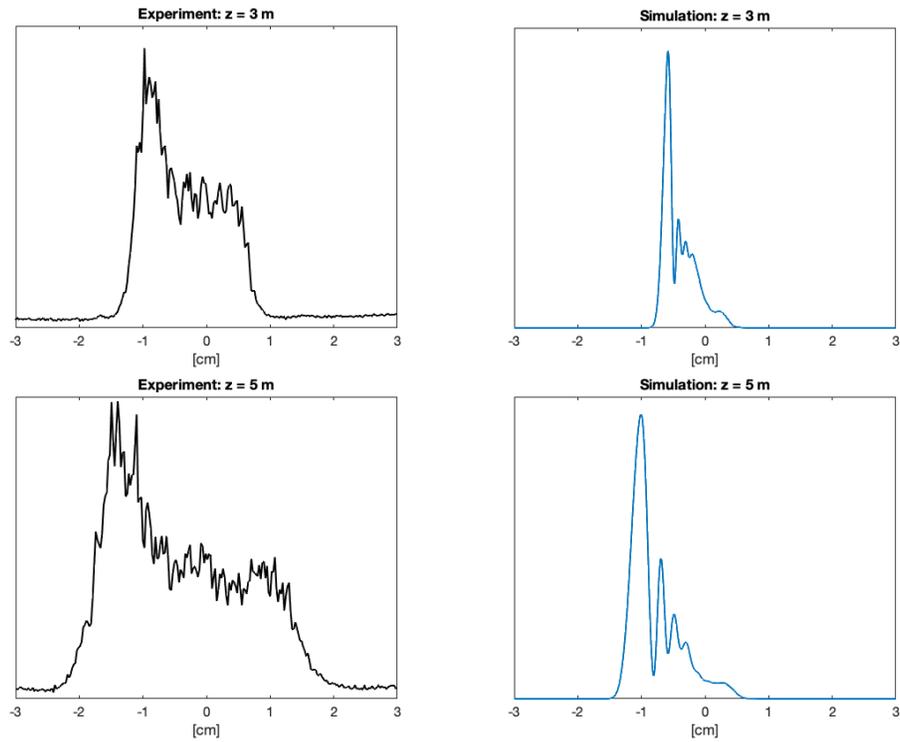


Fig. 8. Irradiance profiles of the simulated and experimental beam at  $P = 5.43$  W along a vertical centerline. The y-axis measures the normalized irradiance, which is plotted against the vertical deviation along the center of the beam spot. Overall, the deflection of irradiance is well captured in the simulations, but the experimental profiles are wider and have less pronounced annular distortions within the beam.

230 therefore the fluctuations in the index of refraction will also increase—leading to increased  
 231 deflection of the beam intensity. Figure 11 depicts the simulated streamlines and temperature  
 232 fluctuations at  $z = 0$  m and  $z = 5$  m for  $P = 5.43$  W, and Figures 9 and 10 plot the steady fluid  
 233 velocity and temperature fluctuation profiles along the  $y = 0$  centerline for the same power and  
 234 distances. Figure 12 provides the peak irradiance and total power of the simulated beam as a  
 235 function of propagation distance.

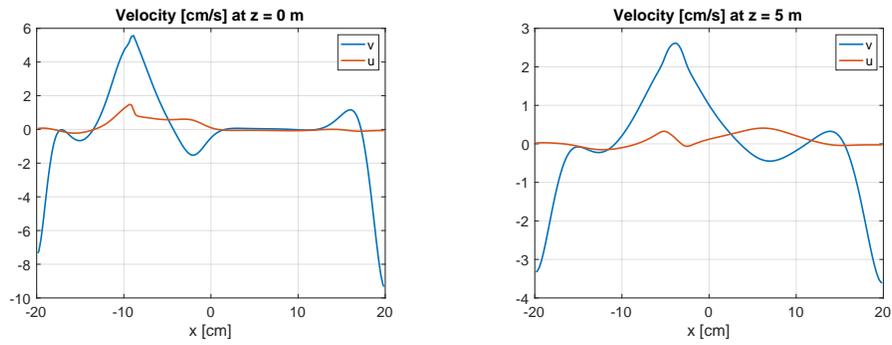


Fig. 9. The steady fluid velocities  $u$  and  $v$  are plotted as a function of the transverse- $x$  coordinate along the  $y = 0$  centerline. At  $z = 0$  m and  $z = 5$  m, the beam is approximately centered at  $x = -8.9$  cm and  $x = -4.9$  cm, respectively. Both  $u$  and  $v$  are positive at the location of the beam spot for each distance, so the local velocity vector points upward and to the right.

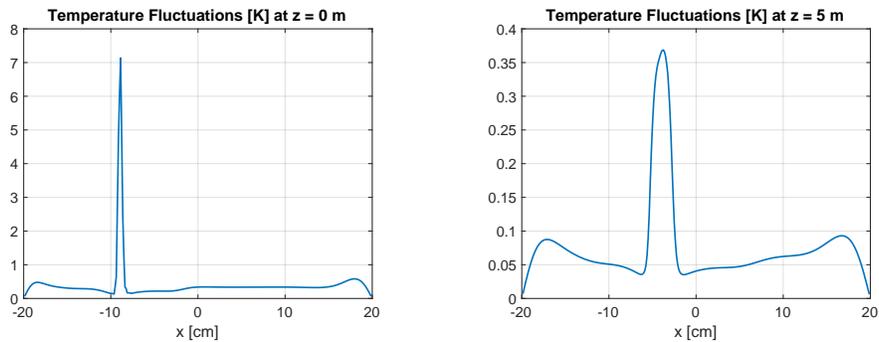


Fig. 10. The steady temperature fluctuation  $T$  is plotted as a function of the transverse- $x$  coordinate along the  $y = 0$  centerline. The temperature fluctuation increases sharply around the location of beam forcing, resulting in sharp refractive index changes as the beam propagates through.

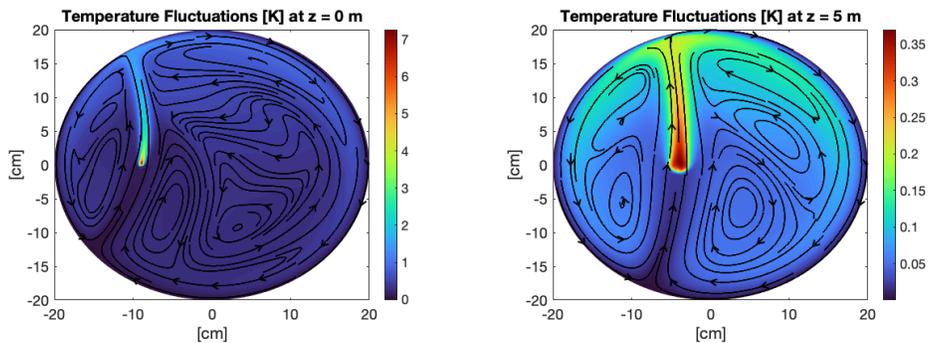


Fig. 11. The temperature fluctuation in degrees K and the streamlines in the fluid at  $z = 0$  m and  $z = 5$  m are provided, respectively. The fluid experiences the most heating at the beginning of propagation before the beam loses energy due to absorption. The asymmetric distribution of the temperature fluctuation about the local beam spot is the mechanism for the deflection characteristic of thermal blooming.

236 The majority of heat deposition into the fluid occurs at the beginning of propagation within the  
 237 chamber. The beam quickly loses intensity as it propagates over the length of the chamber, and  
 238 thus the temperature fluctuation decreases as a function of  $z$  over the transverse chamber domain.  
 239 Since the beam is transversely localized in the negative  $x$ -direction, the temperature fluctuation  
 240 induces a flow with a rightward component. The beam intensity will then deflect in the direction  
 241 of the induced convective flow, which yields the asymmetric crescent in the negative- $x$  direction.  
 242 The departures between the experimental and simulated beam spots can be explained through  
 243 several factors. The reflections of the beam off of the mirrors at the beginning of the chamber  
 244 are not simulated, which is where the beam deposits the most energy along its propagation  
 245 path. There is some uncertainty in the exact value of the absorption coefficient within the  
 246 chamber, which directly influences the amount of energy deposition and subsequent temperature  
 247 fluctuations around the beam spot. Further departures can be due to non ideal Gaussian beam  
 248 quality in the experiment and some uncertainty in the geometry of the experimental setup. The  
 249 largest source of disagreement, however, may come from the comparison between a time-averaged  
 250 experimental beam and a simulated beam in a theoretical steady state. Although the chamber is  
 251 climate controlled, there are still thermal fluctuations from the outside environment that can result  
 252 in a less coherent distribution of temperature fluctuations around the beam spot. After performing  
 253 the time-averaging, many of the irradiance fluctuations become smoothed out in the experimental  
 254 beam, which has the effect of smoothing out some of the thermal distortions. This can partially  
 255 explain the differences in the structure of the distortion rings seen between experiment and  
 256 simulation, along with the other factors mentioned above. In future experiments, it would be  
 257 beneficial to explore ways to reduce thermal fluctuations outside the chamber to achieve a more  
 258 consistent steady fluid flow. To better match the experimental results, the simulation can be  
 259 improved by increasing spatial resolution in the beam field and in the quasi-2D steady flow

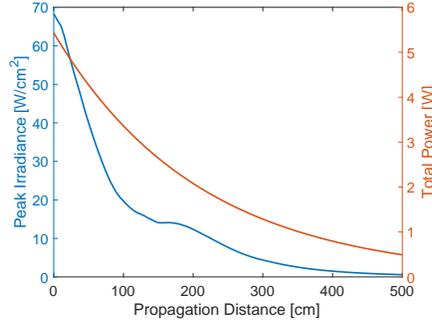


Fig. 12. The peak transverse irradiance (blue) and the total beam power (red) are shown as a function of the propagation distance for the 5.43 W simulated beam. The total power decays exponentially according to the optical extinction coefficient, while the peak irradiance is influenced by spreading, optical losses, and phase distortion.

260 representation, especially in rapidly changing regions in the temperature field.

## 261 5. Conclusion

262 The results of this investigation demonstrate that the flow response to a tilted beam propagating  
 263 off-center within an experimental enclosure can induce asymmetries in the thermally bloomed  
 264 beam spot about the vertical axis. These findings were studied experimentally and via simulation  
 265 with a fully coupled model for laser-fluid interaction. The beam was tuned to a wavelength  
 266 within a water absorption band with a Stanton number equivalent to a high power beam through  
 267 a transmission window. Five different beam powers were investigated, with good agreement  
 268 between the experiment and simulation with respect to the thermally bloomed beam size and  
 269 crescent shape. The methodology of simulation can be used to predict steady-state irradiance  
 270 patterns for future experiments in thermal blooming. Future work should examine thermal  
 271 blooming through a chamber filled with aerosols and the thermal blooming of multiple beams  
 272 combining at a target within a finite chamber.

## 273 Appendix

274 The following is a description of the RBF-FD method utilized to discretize the steady fluid  
 275 equations. Consider the disk of diameter  $\frac{D}{L_x}$  as the computational domain  $\Omega \subset \mathbb{R}^2$  in the  
 276 transverse direction. The components of any  $\mathbf{x}$  in the domain are given by  $\mathbf{x} = \begin{bmatrix} x & y \end{bmatrix}^T$ . At  
 277 each element,  $\mathbf{x}_k$ , of a set of discrete node locations,  $S_N = \{\mathbf{x}_k\}_{k=1}^N$ , the spatial derivatives in  
 278 (1) and (3) are approximated. This is completed by applying the action of the linear differential  
 279 operators to local interpolants of  $\psi$ ,  $\omega$ ,  $T$ ,  $u$  and  $v$  over  $\mathcal{N}_{k,n} = \{\mathbf{x}_{k,j}\}_{j=1}^n$ , which is the set of  $n$

280 points in  $S_N$  nearest to  $\mathbf{x}_k$ .

281 Each local interpolant is a linear combination of (conditionally-) positive definite kernels,  $\varphi$ ,  
 282 evaluated at the points in  $\mathcal{N}_{k,n}$ ,

$$\phi_{k,n,j}(\mathbf{x}) := \varphi \left( \left\| \mathbf{x} - \mathbf{x}_{k,j} \right\|_2 \right), j = 1, 2, \dots, n$$

283 and bivariate polynomial terms,  $\{\pi_{k,l}(\mathbf{x})\}_{l=1}^{M_m}$ , up to total degree  $m$ , with  $M_m = (m+1)(m+2)/2$ .

284 For instance, the local interpolant of a sufficiently smooth function  $f : \mathbb{R}^2 \mapsto \mathbb{R}$  is constructed as

$$s_{k,n,m}[f](\mathbf{x}) := \sum_{j=1}^n \lambda_{k,n,m,j}[f] \phi_{k,n,j}(\mathbf{x}) + \sum_{l=1}^{M_m} \gamma_{k,n,m,l}[f] \pi_{k,l}(\mathbf{x}).$$

285 To ensure that  $s_{k,n,m}[f]$  interpolates  $f$  at the set of points in  $\mathcal{N}_{k,n}$ , the set of coefficients is chosen  
 286 to satisfy the interpolation conditions ( $j = 1, 2, \dots, n$ ),

$$s_{k,n,m}[f](\mathbf{x}_{k,j}) = f(\mathbf{x}_{k,j})$$

287 and the typical constraints to ensure existence of a unique interpolant ( $l = 1, 2, \dots, M_m$ ) (see,  
 288 e.g., [41])

$$\sum_{j=1}^n \lambda_{k,n,m,j}[f] \pi_{k,l}(\mathbf{x}_{k,j}) = 0.$$

289 The interpolant can alternatively be formulated through a change of basis as a linear combination  
 290 of cardinal functions that span the same space. That is,

$$s_{k,n,m}[f](\mathbf{x}) = \sum_{i=1}^n \psi_{k,n,m,i}(\mathbf{x}) f(\mathbf{x}_{k,i}),$$

291 where the new set of basis functions satisfy the cardinal property

$$\psi_{k,n,m,i}(\mathbf{x}_{k,j}) = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}.$$

292 The action of a linear operator  $\mathcal{L}$  on  $f$  at  $\mathbf{x}_k$  is then approximated by

$$(\mathcal{L}f)(\mathbf{x}_k) \approx (\mathcal{L}s_{k,n,m}[f])(\mathbf{x}_k) = \sum_{i=1}^n w_{k,i} f(\mathbf{x}_{k,i}),$$

293 with  $w_{k,i} = (\mathcal{L}\psi_{k,n,m,i})(\mathbf{x}_k)$ . Detailed discussion of the accuracy of this approximation is given  
 294 in, for instance, [31]. The action of  $\mathcal{L}$  at all points in  $S_N$  can then be computed simultaneously  
 295 through the matrix multiplication

$$D\mathbf{f} \approx \begin{bmatrix} \mathcal{L}f(\mathbf{x})|_{\mathbf{x}=\mathbf{x}_1} & \mathcal{L}f(\mathbf{x})|_{\mathbf{x}=\mathbf{x}_2} & \cdots & \mathcal{L}f(\mathbf{x})|_{\mathbf{x}=\mathbf{x}_N} \end{bmatrix}^T \quad (12)$$

296 where the  $k^{\text{th}}$  component of  $\mathbf{f}$  is  $f(\mathbf{x}_k)$ . In this case,  $D$  is an  $N \times N$  matrix that is sparse as long  
 297 as the number of nearest neighbors,  $n$ , is much less than the total number of points,  $N$ . The

298 entries of row  $k$  of the matrix operator are defined as

$$[D]_{ki} = \begin{cases} w_{k,j} & \text{if } \mathbf{x}_{k,j} = \mathbf{x}_i \text{ for some } (k, j) \\ 0 & \text{otherwise.} \end{cases} .$$

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