

## IMAGING AND OPTICAL SYSTEMS

### 1. Introduction to Signals and Linear Systems

### 2. Discrete Systems

(2 weeks)

- a. Matrix description of systems. Unitary and Hermitian systems. Modes
- b. Example. Polarization devices
- c. Example. Modes of an optical resonator
- d. Example. Coupled modes of a waveguide

### 3. Continuous 1D Systems (Temporal Systems)

(2 weeks)

- a. Integral transforms. Shift-invariant systems
- b. 1D Fourier transform and its properties
- c. Linear shift-invariant systems. Impulse response function. Convolution. Transfer function
- d. Example: Propagation of an optical pulse in a dispersive medium

### 4. Continuous 2D Systems (Spatial Systems)

(2 weeks)

- a. 2D Fourier transforms and its properties
- b. Projection-slice theorem. Application to CT tomography
- c. 2D linear systems. Point spread function. Transfer functions. Spatial filters

### 5. Coherent Optical Systems

(3-4 weeks)

- a. Expansion of arbitrary waves in terms of plane waves. Angular spectrum
- b. Transfer function of free-space propagation. Fresnel diffraction. Analogy between diffraction and dispersion
- c. Hermite-Gaussian beams as resonator modes.
- d. Non-diffracting beams. Talbot imaging
- e. Image formation as a linear system. Point spread function and transfer function. Resolutions
- f. Optical Fourier transform. Optical spatial Filtering
- g. Imaging phase objects. Phase contrast microscopy
- h. Laser scanning imaging system. Point spread function and depth of focus.

### 6. Incoherent Imaging Systems

(2-3 weeks)

- a. Image formation with incoherent light. PSF, OTF, and MTF of diffraction-limited system
- b. Effect of defocus and aberration on PSF, OTF, and MTF
- c. Confocal microscopy
- d. Laser scanning fluorescence microscopy

### \*7. Scattering Systems

(1 week)

- a. Rayleigh scattering. Born approximation
- b. Optical diffraction tomography